#### KernelGen – a toolchain for automatic GPU-centric applications porting



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# Motivation and targets

#### Motivation

- The need to port huge numerical models on GPU: no <u>computational "kernel"</u>, individual model blocks have too small self perf impact (~10%), resulting into small speedups, if only one block is ported (the figure below is for COSMO model)
  - → too hard to port models on GPU by hand



#### Motivation

- Most of the modern numerical weather prediction models are not suitable for manual parallelization due to enormous code base size:
  - $\rightarrow$  too hard to port models on GPU by hand

Model	Developer	Lines of code
COSMO 4.13	DWD	187K
WRF 3.3	NOAA/NCAR	370K
AROME/ARPEGE	METEOFRANCE	2280K

#### Motivation

- In well-known study on porting WSM5 block of the WRF model with OpenACC directives 40-60% of time is spent on communications
  - → intensive CPU ↔ GPU data transfer may introduce significantly negative performance impact

The number of CPU cores and GPUs	Total time (seconds)	The time of transfers	The time of computations
1 / -	236		
4 / -	70		
1/1	19.72	10.75	8.85
2/2	12	6.87	5.29

Michael Wolfe, Craig Toepfer – Porting WRF

#### Targets

- Create runtime environment capable of executing original CPU applications on the GPU without code modifications
- Minimize data transfers by keeping all the application data in GPU memory and automatically porting onto GPU as much code as possible



Idea

- Many computational kernels, single main kernel
- Minimize data transfers by performing some serial computations on the GPU
- + Use DragonEgg/LLVM/Polly:
  - Support many programming languages
  - Automated search for potentially parallel code blocks
  - → Automated generation of GPU kernels

- Main host system and peripheral GPU:
  - Transfer data from host to GPU
  - Launch the GPU kernel and wait for completion
  - Transfer results back from GPU to host



- Main <u>host system</u> and peripheral <u>GPU</u>:
  - Transfer data from host to GPU
  - → Launch the GPU kernel and wait for completion
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- Main host system and peripheral <u>GPU</u>:
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Transfer results back from GPU to host

Main <u>GPU</u> and peripheral <u>host-system</u>:

Port on GPU as much source code as possible, except host-only functions (I/O, syscalls, ...)



GPU kernels of individual computational loops



# Key results

#### Results

- KernelGen can recognize parallel loops in simple tests and can generate GPU kernels with efficiency comparable to PGI Accelerator
- KernelGen successfully compiles major NWP models: WRF, COSMO and SLM (ПЛАВ)
- Complexity: half-year work of 2 developers, based on many other projects

Performance and register footprint of CUDA kernels generated with KernelGen and PGI:

Kernel	KGen time	KGen #regs	PGI time	PGI #regs	CPU time
sincos	0.00390	9	0.00357	29	0.64972
jacobi_1	0.02063	24	0.02862	17	1.05245
jacobi_2	0.01233	7	0.01206	10	0.10387

In some cases kernels generated by KernelGen and PGI are significantly different, but performance is always comparable



KernelGen from the user point of view

#### User interface

- KernelGen can generate GPU code out of any language supported by the gcc compiler frontend
- KernelGen compiler flags are fully compatible with gcc (except the LTO logic, which is replaced by custom IRcode link step)
- Required additional GPU configuration parameters are provided through the environment variables (kernelgen\_runmode, kernelgen\_verbose, kernelgen\_szheap, ...)

# Compile application for KernelGen

\$ make cd kernelgen && make make[1]: Entering directory `/home/marcusmae/Programming/kernelgen/tests/perf/sincos/m alloc/kernelgen' kernelgen-gfortran -c ../sincos.f90 -o sincos.o KernelGen : NumExtractedLoops = 1 CurrentFunction: "sincos\_" CurrentHeader: "21.orig.header" KernelGen : NumExtractedLoops = 2 CurrentFunction: "sincos " CurrentHeader: "12.orig.header' KernelGen : NumExtractedLoops = 3 CurrentFunction: "sincos " CurrentHeader: "3.orig.header" kernelgen-gcc -std=c99 -c ../main.c -o main.o KernelGen : NumExtractedLoops = 1 CurrentFunction:"main" CurrentHeader: "6.orig.header" kernelgen-gfortran sincos.o main.o -o sincos \$

```
[marcusmae@noisy malloc]$ kernelgen_verbose=1
kernelgen_runmode=1 kernelgen_szheap=$((1024*1024*1024))
kernelgen/sincos 512 512 64
Using KernelGen/CUDA
```

Building kernels index ... \_\_kernelgen\_sincos\_\_loop\_21 \_\_kernelgen\_sincos\_\_loop\_12 \_\_kernelgen\_sincos\_\_loop\_3 \_\_kernelgen\_main\_loop\_6 \_\_kernelgen\_main

```
Launching kernel __kernelgen_sincos_loop_3
    blockDim = { 32, 16, 2 }
    gridDim = { 16, 32, 32 }
    _kernelgen_sincos_loop_3 time = 0.00407996 sec
only the kernel execution time = 0.00390173 sec
```

# Compile application for PGI

```
$ make
cd pgi && make
make[1]: Entering directory
`/home/marcusmae/Programming/kernelgen/tests/perf/sincos/malloc/pgi'
pgfortran -fast -Mnomain -Minfo=accel -ta=nvidia:4.1,time
-Mcuda=keepgpu,keepbin,keepptx -c ../sincos.f90 -o sincos.o
sincos:
```

- 12, Generating copyin(y(:nx,:ny,:nz))
   Generating copyin(x(:nx,:ny,:nz))
   Generating copyout(xy1(:nx,:ny,:nz))
- 13, Loop is parallelizable
- 14, Loop is parallelizable
- 15, Loop is parallelizable Accelerator kernel generated
  - 13, !\$acc do parallel, vector(4) ! blockidx%y threadidx%z
  - 14, !\$acc do parallel, vector(4) ! blockidx%x threadidx%y
  - 15, !\$acc do vector(16) ! threadidx%x

pgcc -c ../main.c -o main.o pgfortran -fast -Mnomain -Minfo=accel -ta=nvidia:4.1,time -Mcuda=keepgpu,keepbin,keepptx sincos.o main.o -o sincos make[1]: Leaving directory `/home/marcusmae/Programming/kernelgen/tests/perf/sincos/malloc/pgi' \$

```
$ pgi/sincos 512 512 64
Accelerator Kernel Timing data
home/marcusmae/Programming/kernelgen/tests/perf/sincos/mal
loc/pgi/../sincos.f90
  sincos
    12: region entered 1 time
        time(us): total=2362577 init=2268435 region=94142
                  kernels=3575 data=86839
        w/o init: total=94142 max=94142 min=94142
avg=94142
        15: kernel launched 1 times
            grid: [128x16] block: [16x4x4]
            time(us): total=3575 max=3575 min=3575
avg=3575
```



#### KernelGen from the developer point of view

# Compiling and linking

- Port whole code on the GPU
  - Compiling and linking
  - ➔ Problem: no linker for GPU code
    - Compile parts of the code for GPU and link them manually, inlining everything into main kernel and loops kernels
    - → CUDA-compiler exists only for C/C++ code
- Automatically extract parallel loops
  - → Analyze simple AST or specialized IR?
    - → Parse high-level language or its AST (Rose, XML) → waste of time
    - → Parse intermediate representation (LLVM IR)

#### Components

- **LLVM** the modular analysis and transformation system, working with the specialized intermediate representation (LLVM IR)
- DragonEgg the gcc plugin, which converts gimple into LLVM IR, i.e. original program may be written in any language supported by gcc
- **Polly** the loop optimization engine for LLVM IR
- C Backend generates C code for the given LLVM IR module

# Application runtime design

- Binary image still contains fully working host code used by default; GPU version is activated by request
- Almost all the code is running on the GPU
  - → Some parts of the code is not possible to port (functions in external libraries, system calls) → external host calls are supported
- All data is stored in GPU memory and is offloaded to host only by request
- The main kernel is persistent on the GPU during the whole application lifetime → hacks to overcome some limitations of CUDA, concurrent kernels execution

# Handling host-only calls

- Example: atoi(<address\_in\_gpu>);
- Launch CPU function and synchronize data by request
  - SIGSEGV handler to catch GPU memory range accesses during the host call
  - mmap host memory pages onto GPU memory ranges and fill them with GPU data; synchronize data back after the function is finished
- Interaction model: "active" GPU, "passive" host (GPU initiates kernels launches and host calls)

# Generating parallel loops

- Loop iterations dependency checks
  - ➔ Runtime Alias Analysis
  - → LLVM Polly, ClooG
- Generate LLVM IR for GPU kernels
  - → GPU extensions for Polly
- Determine the GPU kernel compute grid
  - Substitute kernel arguments
- Runtime-optimization of loops GPU kernels
  - → Substitute compute grid parameters, optimize LLVM
  - → Cache the analysis results

#### KernelGen uses JIT-compilation

- Kernel arguments substitution
  - → Runtime Alias Analysis
  - Determine the optimal compute grid parameters
- Substitute the compute grid parameters
  - Helps to reduce the register footprint



# LLVM Polly

# LLVM Polly: a tool for loop transformations

• Polly is able to transform loop with dependent iterations (a) into loop with parallel iterations (b):



Illustrations (c) Tobias Grosser

# LLVM Polly: a tool for loop transformations

• Polly is able to transform loop with dependent iterations (a) into loop with parallel iterations (b):

```
for (i = 1; i <= n; i++) {
             for (j = 1; j < i + m; j++)
(a)
               A[i][j] = A[i-1][j] + A[i][j-1]
            A[i][i+m+1] = A[i-1][i+m] + A[i][i+m]
           parallel for (p = 1; p <= m+n+1; p++) {
             if (p >= m+2)
               A[p-m-1][p] = A[p-m-2][p-1]
(b)
             for (t = max(p+1, 2*p-m); t <= p+n; t++</pre>
               A[-p+t][p] = A[-p+t-1][p] + A[-p+t][p]
           }
```

Code examples (c) Tobias Grosser

# LLVM Polly: capabilities

- Search for valid SCoPs in LLVM IR
- Optimizations:
  - → Split loops

 $\rightarrow$ 

- Transform loops polyhedra
- Loops interchanging

- Detect parallel loops
- Generate CLooG AST
- Generate LLVM IR out of CLooG AST

– used by KernelGen

# Static Control Part (SCoP)

- Polly works with ScoPs parts of the program with the following properties:
  - Structured control flow counting variables, conditions
  - Loop boundaries, array indices and conditionals are affine expressions of parameters and induction variables
  - All operations (including function calls) do not have side effects
- For ScoPs it is possible to determine:
  - Iterations polyhedras and the order of iterations inside them
  - Memory access patterns

# Semantic SCoP

 Polly can detect the semantic ScoPs, i.e. not only indexed for-/do- loops, but any code parts that behave like indexed for-/do- loops:



Code examples (c) Tobias Grosser

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#### Code examples (c) Tobias Grosser

# Polly is not enough!

• In real-world applications compile-time info is often insufficient to detect the parallel loop



- In runtime more accurate alias analysis could be performed after substituting the values of pointers and checking the used memory intervals for intersection
  - An argument to postpone loop analysis for runtime (JIT-compilation)
- For each pointer operation the access function is computed:

f(<the\_number\_of\_iteration>)

• With help of the ISL library, the problem of linear programming is solved: *find the* **f** *maximum and minimum values in the given iterations space* 

- After substitution the pointer value in known, as well as its maximum and minimum relative offsets
- → Thus, it is possible to compose the memory intervals:

```
0 <= i < 100
0 <= j < 200
ptr = (int*)322636916
f(i,j) = i * 200 + j
```

```
f_minimum = 0
f_maximum = 19999
interval:
  [322636916, 322716914]
```

- For each pointer use we determine the memory interval
- If some memory write interval
  - ➔ Intersects with another write interval
  - Or intersects with read interval
  - Then the kernel is **not** parallel!

#### Generating CUDA kernels

- Polly codegen was modified in order to:
  - Determine the GPU thread indices in compute grid (GridDim, BlockDim, BlockIdx, ThreadIdx)
  - → Map loop iterations space onto GPU threads space

# Generating CUDA kernels

- Organization of iterations-threads mapping:
  - All threads perform the same number of iterations
  - Threads with sequential indexes perform the sequential iterations

#### → Coalescing memory transactions

- Support for mapping iterations space onto any compute grid space (extra inner loops)
- Recursive analysis of nested loops:
  - Utilize GPU capabilities for multidimensional compute grids creation
  - The most inner loop always correspond to the "x" axis of the GPU compute grid

# Computing the optimal GPU compute grid

- After substituting the kernel arguments the loops dimensions become known
- With known loops dimensions it is possible to compute the optimal compute grid configuration:
  - Minimize the number of unused threads
  - Specify the number of iterations to perform in each thread

# Runtime-optimization of loops' kernels

- Initially the "universal" LLVM IR is generated for kernel loops: one thread may perform more than one loop iteration
- Upon the kernel launch, the used compute grid becomes known
  - Extra IR-code optimizations could be performed after substituting the known constants
  - → Reduce the register footprint
  - → Eliminate fictive loops, less branching



# Development plan

#### Programming

- Implement recursive nested loops analysis already implemented during PCT conf <sup>(C)</sup>
- Privatize the global variables (no linker for GPU code)
- Re-implement host code JIT-compiler similar to lli
- Restructure the project source code (need better design)
- Implement kernels versions switcher heuristics and test it in real applications

#### Programming

- Optimizing data synchronization between CPU and GPU (#82, #84)
- Implement kernels configurations cache
- Implement application computational profile dumping for further reuse

#### Testing

- Test KernelGen on benchmarks and target applications:
  - → Polybench, NPB, SPEC CPU 2006
  - → COSMO, WRF, SLM, MF-RAPS
- Bug fixing



# http://kernelgen.org



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• Instructions available at project wiki pages:



#### Resources

- The LLVM Compiler Infrastructure
- Polly: Polyhedral optimizations for LLVM
- DragonEgg Using LLVM as a GCC backend